https://wiki.teltonika-gps.com/view/DashCam_Configuration

DashCam Configuration

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FMX125/225 configuration

- Please make sure to download the latest DashCam FW version. The latest FWs can be downloaded from the following Wiki page <u>DashCam Firmware errata</u>
- It is necessary to change Data Protocol to Codec 8 Extended

Data Protocol



• In RS232\RS485 settings change Mode to RS232 and in RS232 Mode select DashCam



• Make sure to change I/O Camera state Priorities to Low

	Input Name	Units	Priority				Low Level	High Level	Event C	nly		Operand	Aug Const
CPRS	BLE Fuel Level #2	iounts.	None	Low	High	Paric	0 0	0 🔅	Gash	Yes	No	Monitoring	*
MS1 Call Services	BLE Fuel Level #3	ioants.	None		High	Panic	0.0	0.0	Gash		No	Monitoring	¥
25M Operators	BLE Fuel Level #4	ioants.	None		High	Panic	0.0	0.0	Granh		No	Monitoring	¥
Features	BLE Luminosity #1	b.	None		High	Panic	0.0	0 2	Crash		No	Monitoring	¥
erometer Features	BLE Luminosity #2	b	None		High	Panic	0.0	0 2	Cash		No	Monitoring	¥
uto Geofence	BLE Luminosity #3	b.	None		High	Panic	0.0	0 2	Granh		No	Monitoring	*
musl Geofence	BLE Luminosity #4	b.	None		High	Paric	0 0	0 2	Gash		No	Monitoring	~
ip \ Odometer	BLE Fuel Frequency #1		None		High	Partic	0 0	0 2	Gash		No	Monitoring	~
Bartoch	BLE Fuel Frequency #2		None		High	Partic	0 0	0 🚔	Cash		No	Monitoring	*
Buetooth 4.0	BLE Fuel Frequency #3		New		High	Paris	0.0	0 🔅	Gash		No	Monitoring	~
Reacon Let	BLE Fuel Frequency #4		None		High	Paric	0.0	0 🙏	Gash		No	Monitoring	~
10	Battery Level %	1.	None		High	Panic	0.0	0 🙏	Gradh		No	Monitoring -	~
0101	BT Status		None		High	Panic	0.0	0.0	Crash		No	Monitoring	v .
CAN Adapter	UL202 Fuel Level		None		High	Panic	0.0	0 2	Crash		No	Monitoring	¥
52321.45485	UL202 Status	-	None		High	Panic	0.0	0.0	Cranh		No	Monitoring	v
	Pulse Counter DIN1	-	Nove		High	Pank	0.0	0.0	Granh		No	Monitoring	~
	Coordinates (506709		None		High	Partic			Grants		No	Monitoring	~
	Ignition On Counter		None		High	Partic	0 0	0.2	Gash		No	Monitoring	~
e e 🔊 🖓 e e e e e	Front Camera State	-	No.	1	14.5	Party	0.0	. *	and a	-		Monitoring	~

• Do not forget to configure *DashCam* server information. In RS232\RS485 fill in DashCam Server Settings with *Domain* and *Port* entries.

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Metadata version

From 03.29.00.Rev.534 metadata version can be configured. Version descriptions and differences are provided in section.

<u>https://wiki.teltonika-gps.com/view/DashCam_Communication_Protocol#Communication_protocol</u> . Default value is version 3.

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FMC650 DashCam Configuration

(!) Required firmware version - 03.00.14.Rev.114. Firmware errata.

• Make sure Data Protocol is set to Codec 8 Extended

Data Protocol



• In *RS232* \ *RS485 settings tab*, make sure to enable **Camera interface** by "Enable", and select **DashCam** in the Mode drop-down menu, afterwards **DashCam COM1** and **Camera I/O** should appear in the tab list.

LVCAN					
FMS IO	COM1 settings				
FMS ECO Driving	Camera inte	erface		_	
Manual CAN IO	Disab	le	Enable		
al CAN Requests	Mode	Silent N	Mode	~	
CAN Commands	Baudrate	Baudrate Default		~	
achograph Data	COM2 setti	nas			
232 \ RS485	Camera int	erface			
\ Tachograph	Disab	le	Enable		
ressureCheck	Mode	Silent N	Node	~	
Scenarios	Baudrate	Default		~	
bileye		2 210 011			
Reefer IO					

• Make sure to change Camera I/O camera state Priorities to Low

Camera I/O									
Input Name	Units	Priority							
COM1 DashCam camera state		None	Low	High	Panic				

• In appeared *DashCam COM1* tab, make sure to **configure everything by your needs**, and do not forget to complete the "**Domain**" and "**Port**" settings in "*DashCam*" *Scenario Settings*

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• **NOTE:** This is a base setup for the device to work properly. Other device configuration is

made according to your needs.

• **NOTE:** There are different settings for picture quality and compression, these settings will affect picture/video sizes and upload speeds. For more information about transfer sizes and timings, please visit our <u>DashCam Data Transfer Timing</u> section

Connecting two cameras simultaneously for FMx650

The new feature for FMx650 DashCam configuration, which is available from **03.00.14.Rev.114 iCamera** allows you to connect two of your cameras at once. Method for connection and configuration stays the same, for this you are only required to choose **two** cameras in "**RS232** \ **RS485**" tab from the configurator.

In the new functionality, you are able to connect any combo of the cameras by your wish, as an example: you are able to connect *DashCam/Dualcam*, *DashCam/DSM*, *DSM/DSM*, *DualCam/DualCam* and etc.

Manual CAN IO							
Manual CAN Requests] _ R	RS232 Settings					
Manual CAN Commands]	COM1 settings					
Tachograph Data		Camera inte	erface				
RS232 \ RS485		Disab	le	Enab	le		
CAN \ Tachograph		Mode	Silent Mo	ode	``		
ContiPressureCheck		Baudrate	Default				
Custom Scenarios							
Mobileye]	COM2 setti	ngs				
Reefer IO		Camera inte	erface				
Transcan 2 IO		Disab	le	Enab	le		
Transcan Advance IO		Mode	Silent Mo	de	`		
Euroscan IO		Baudrate	Default		`		
TK Touchprint IO							
Simbiotecha PLC IO	1						

Camera Scenario Mode

The options On Ignition and Always determine the working mode.

On Ignition means the camera scenarios will operate the way it was up to **03.27.13.Rev.662**, that is it will work only when the ignition is detected.

Always mode means the camera scenarios will work all the time, including whenever the device is in sleep mode (except Ultra sleep mode during which the scenario is disabled). During sleep footage

requests (if the network is available), periodic image sending and triggers work as well.

Warning: using Always mode, depending on the configuration, the device might wake up from sleep very frequently. That has to be taken into consideration when configuring the scenarios.

Periodic image sending scenario

Periodic image sending triggers photo capture from a front camera, whenever the timeout is reached (sending interval parameter).

Update: Since 03.27.13.Rev.662 firmware, Periodic Image Sending Enable/Disable switch was replaced by a camera selection:

- Front cameras deselected periodic image sending is disabled (value 0)
- Front camera selected front camera's pictures will be sent periodically (value 1)

If the camera has not finished uploading pictures to the server, then the photo capture is skipped.

File Transfer priority

Filet transfer priority allows changing the priority of the specific type (photo or video) when both types are ready at once. The file transfer priority can be the following:

- Picture the photo type of files will be prioritized.
- Video the video type of files will be prioritized.
- Alternating the priority will be changing from picture to video and vice versa after each file transmission.

cantera i catare setti	ngs								
Camera Picture Resol	ution								
160 x 120 320 x 240									
640 x 480		1280 x 720							
1920 x 1080									
Camera Picture Comp	50 🗘								
OSD Display									
Disablo		Enable							
Disable									
Video Frame Rate	25 FPS		~						
Video Frame Rate File transfer priotity	25 FPS Picture		×						
Video Frame Rate File transfer priotity Camera Time Zone	25 FPS Picture UTC+00	:00	~ ~ ~						

Camera RTC synchronization

Camera RTC synchronization is done anytime the device itself is synchronized (via NTP, NITZ or GNSS).

After 03.27.13.Rev:662 firmware for FMX125 we added a feature to set camera time, same as device selecting time.

OSD Display

Disable	Enable				
Video Frame Rate	25 FPS	~			
File transfer priotity	Alternating	~			
Camera Time Zone	UTC+00:00	~			

NOTE:

That after changes of the time it can be that you can receive files which the old-time or just do not have any video/photo on this periodical time then you change time, but then it will be back to normal work.

Time zone changes the inside clock of the camera, not only the OSD displayed time but all recordings will be done according to that.

For example, if you request a video from, say, 9:00 AM GMT+0, and the camera time is GMT+0 (matches our device's time), it is all fine. But if you were to configure time zone later to, for instance, GMT+10, the camera time will be set according to that time zone (time forwarded by 10 hours in this case). Which means that time gets forwarded with no real continuation as the camera does not understand the concept of time zones, it just uses time that we set. For continuation reasons in our device, we continue using GMT+0 in the camreq and then compensate with time zone if needed. The result of that, if we send the same request command as before (when requesting 9:00 AM video) with time zone GMT+10 set, the camera will receive video request for 7 PM (19:00) and the videos were not recorded at that time which will result in "file doesn't exist".

Camera control using DOUT1

It is possible to control the camera ON/OFF state using DOUT1 control in the "Features" selections. In order to achieve

this functionality, please see the connection diagram located in the First start page.



DOUT 1 Output Type has selections of either normal or inverted. Selecting inverted will make the DashCam turn on when the DOUT1 state will be 0 and turn off the the state changes to 1 and vice versa. This is recommended as inverted selection will turn on the camera upon turning on you FMx device. When 'Normal' is selected, you will need to send an SMS message to the device requesting to turn on DOUT1 every time **IF DOUT control via ignition** is not turned on.

Dout control via ignition stands for controlling DOUT when the ignition turns on, this setting can be chosen instead of Inverted dout. Please make sure ignition settings in the 'System' tab is correctly set and the device will turn on when the ignition of the vehicle is on. **Ignition Off Timeout** is a specified amount of seconds which the device will wait after ignition turns off before turning the device off. If the ignition comes back within the specified timeframe, timeout will turn off and the camera will not be turned off.

DOUT deactivation via DIN turns of DashCam when the state of DIN1 changes. This can be set with a button which when pressed will disable DOUT1 thus ensuring camera has no power.

DOUT control can also be set using sms command such as **setdigout**.

"*setdigout # Y1 Z1*" The complete setdigout command structure, listed below is explanation:

- # 0; 1 or ? (0 OFF, 1 ON, ? Ignore) for DOUT1.
- Y1 timeout value for DOUT1 if needed (in seconds).
- Z1 maximum speed value for DOUT1 if needed.

Crash Detection Functionality using DOUT

The crash detection feature is a crucial capability provided by our device. It enhances evidential documentation through video or photo evidence in the event of a crash. However, activating this functionality necessitates a direct connection of the camera to a power source. Nonetheless, such a direct connection can lead to **battery drainage**.

To circumvent this issue, we recommend utilizing DOUT and a relay for connection. This setup enables control via SMS or GPRS command, or through predefined scenarios within our device. By activating DOUT post-ignition, the camera receives power, allowing it to function and record evidence even after the ignition is turned off following a crash. **For your convenience, the connection scheme can be found here:** <u>DashCam First Start</u>

It is important to note that in the event of a fatal crash where fatalities may occur, we cannot guarantee the retrieval of video or photo evidence due to the severity of the accident. Moreover, both the camera and the device itself may sustain irreparable damage in such instances

Other camera related functionality

Camera is configured if all of these conditions are met:

- 1. RS232 mode is selected (DashCam)
- 2. Camera was not configured since startup or one of the related parameters were

changed (compression, framerate or OSD)

3. Camera file transfer is not active

Active camera reconfiguration is accompanied by two consecutive camera shutter clicks. If camera is disconnected and later reconnected, a device will detect it by periodic camera ping packet. Once camera is detected, the device will reissue the reconfiguration procedure.