

# FMC125 I/O settings

[Main Page](#) > [Professional Trackers](#) > [FMM125](#) > [FMC125 Configuration](#) > **FMC125 I/O settings**

□

## Contents

- [1 Input Name](#)
- [2 Current Value](#)
- [3 Units](#)
- [4 Priority](#)
  - [4.1 None Priority](#)
  - [4.2 Low Priority](#)
  - [4.3 High Priority](#)
  - [4.4 Panic Priority](#)
- [5 High and Low Level](#)
- [6 Event Only](#)
- [7 Operands](#)
  - [7.1 Operand On Exit](#)
  - [7.2 Operand On Entrance](#)
  - [7.3 Operand On Both](#)
  - [7.4 Operand Monitoring](#)
  - [7.5 Operand On Hysteresis](#)
  - [7.6 Operand On Change](#)
  - [7.7 Operand On Delta Change](#)
- [8 Avg Const](#)
- [9 Send SMS To](#)
- [10 SMS Text](#)
- [11 FMC125 RS-232/RS-485 parameter configuration](#)
  - [11.1 RS-232 modes](#)
    - [11.1.1 RS-232 baudrate and parity](#)
    - [11.1.2 RS-232 TCP Binary mode settings](#)
    - [11.1.3 RS-232 Garmin mode settings](#)
  - [11.2 RS-485 modes](#)
    - [11.2.1 RS-485 baudrate](#)
    - [11.2.2 RS-485 LLS sensors](#)

When no I/O element is enabled, AVL packet comes with GNSS information only. After enabling I/O element(s) AVL packet contains current value(s) of enabled I/O element(s) along with GNSS information.

## Input Name

I/O element name.

## Current Value

If device is connected to **Configurator** all current I/O values are displayed in this column. Also I/O current values can be seen in [Status→I/O Info](#) tab.

## Units

Units of measurement.

## Priority

This field allows to enable I/O elements and setting them a priority so they are added to the data packet, which is sent to the server. By default **12 I/O elements** with **Low priority** are enabled: Ignition, Movement, Data Mode, GSM Signal, Sleep Mode, GNSS Status, GNSS PDOP, GNSS HDOP, External Voltage, Speed, Battery Current, Battery Voltage. All records made by FMC125 are regular, and regular packets are sent as low priority records.

Priority level (AVL packet priority) can be:

### None Priority

Module doesn't make additional record.

### Low Priority

Module makes an additional record with an indication that the **event was caused by an I/O element change** (depending on [Operands](#) configuration).

### High Priority

Module makes an additional record with High priority flag and **sends event packet immediately** to the server using **GPRS**.

### Panic Priority

This priority triggers same actions as **High priority**, but if GPRS fails, it sends an AVL packet using **SMS data** if SMS data sending is enabled and the number is provided in [SMS/Call Settings](#).

## High and Low Level

These levels define I/O value range. If I/O value **enters or exits** this range, FMC125 **generates an event**.

## Event Only

When this is selected, I/O element status value will be **appended only to eventual records**, otherwise I/O element status value will appear in each AVL record.

# Operands

Defines when to generate event: [On Exit](#), [On Entrance](#), [On Both](#), [Monitoring](#), [On Hysteresis](#), [On Change](#) or [On Delta Change](#).

## Operand On Exit

Record is generated when input value leaves a range between low and high level limits.



## Operand On Entrance

Record is generated when input value enters a range between low and high level limits.



## Operand On Both

Record is generated by both *On Exit* and *On Entrance* operands' logic at same time.



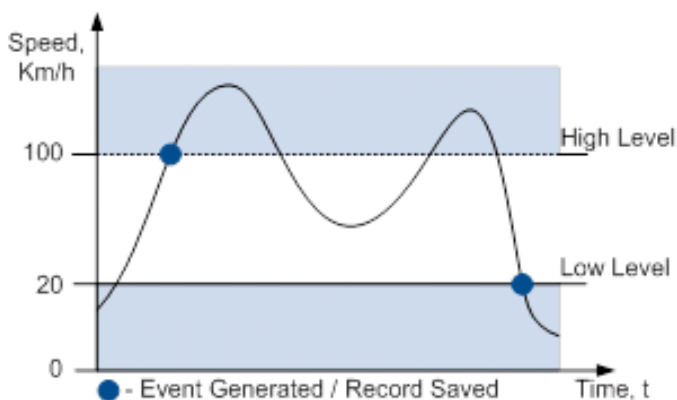
## Operand Monitoring

No event at all. Values are recorded only when other triggers worked.



## Operand On Hysteresis

Record is generated when input value crosses the high limit value from below the low limit value or vice versa.



## Operand On Change

---

Record is generated when input value changes.



## Operand On Delta Change

---

Record is generated when input value changes and the absolute change becomes equal to or higher than the limit value.



## Avg Const

If *Avg Const* value is 10, new value must be present for 1 second to register the change to a new value. Internal sampling is done every 40 ms, so 25 samples are taken per second. To configure 5 seconds of averaging multiply 10 by 5 yielding 50 as *Avg Const* value. The same logic works if the device is in [Deep Sleep mode](#).

Averaging follows RC exponential curve, see image below:



For Boolean values of  $5\tau$ , values is used, that means value change is taken when new values is averaged to more than 99.3%.

***NOTE: Average Constant is not used as an activation timer or delay timer. But it is used as a filter.***

Event is generated at different times due to variations in voltage. Average constant is designed to filter jumps instead of event generation time.

For example: generation is set to happen at 14500mV, and actual voltage is set to 15000mV, that record will be generated earlier than 10s with avg const set to 100. This is because avg const is calculating time it takes for device to get to actual voltage (in this case 15000 mV), while device will be generating records when it hits 14500mV.

## Send SMS To

Sends SMS notification about event to selected number from [SMS/Call Settings](#) **GSM Predefined Numbers** list if event priority is set to [Low](#), [High](#) or [Panic](#).

## SMS Text

The SMS Text field can be altered and any text can be entered. Maximum message length is **160** symbols (numbers, letters and symbols in ASCII, except for comma “,”).

SMS Event Text may be either in default or composed format.

**Default format:**

Date, time, longitude, latitude, 'SMS text', value

Example:

2018/11/02 12:00:00 Lon:0.000000 Lat:0.000000 Alarm 1

**Composed format:**

Composed format may consist of text and defined commands which start with % symbol.

**Supported commands:**

Command	Description
<b>imei</b>	IMEI
<b>fw</b>	Firmware version
<b>fullfw</b>	Full firmware version
<b>modem</b>	Modem firmware version
<b>gnss</b>	GPS firmware version
<b>vin</b>	OBD VIN number
<b>lat</b>	Latitude (non-float value)
<b>lon</b>	Longitude (non-float value)
<b>sat</b>	Satellites in use
<b>time</b>	Timestamp
<b>din1</b>	Digital Input 1
<b>din2</b>	Digital Input 2
<b>din3</b>	Digital Input 3
<b>ain1</b>	Analog Input 1
<b>out1</b>	Digital Output 1
<b>out2</b>	Digital Output 2
<b>pdp</b>	PDOP
<b>hdp</b>	HDOP
<b>exv</b>	External Voltage
<b>gmap</b>	Google Maps link
<b>mov</b>	Movement
<b>odo</b>	Trip Odometer
<b>op</b>	GSM operator
<b>spd</b>	Speed
<b>ib</b>	iButton
<b>mod</b>	Data Mode
<b>sig</b>	GSM signal
<b>slp</b>	Sleep Mode
<b>cel</b>	Cell ID
<b>lac</b>	Area Code
<b>tmp</b>	Dallas Temperature 1
<b>mac</b>	BT MAC address

**dtc** OBD fault codes  
**flat** Latitude (float value)  
**flon** Longitude (float value)  
**date** Date in yyyy/mm/dd format  
**datetime** Time in hh:mm:ss format  
**val** Eventual IO value  
**io'par\_id'** Element value by parameter ID

### Composed text example:

%imei Movement %io50010

### Event SMS text:

352094082828606 Movement 1

If FMC125 is in [Deep Sleep](#) or [Ultra Deep Sleep](#) mode and an SMS event occurs with [Low priority](#) (which does not wake up FMC125), then the device does not send the message. It is saved to device memory until it wakes up from [Deep Sleep](#) or [Ultra Deep Sleep](#) mode and GSM modem starts working normally. After it wakes up, all the messages that are saved to memory will be sent, but keep in mind that only 10 messages can be saved to memory - all other messages will not be saved, until there is free memory space.

## FMC125 RS-232/RS-485 parameter configuration



FMB-125 supports RS-232 and RS-485 serial standards and can be configured to work in different RS-232/RS-485 modes. More information about each mode is provided in [RS-232 and RS-485](#). Only one mode may be selected at a time:

- [Disable](#) - Disable RS-232/RS-485 functionality;
- [RS232](#) - Select RS-232 functionality;
- [RS485](#) - Select RS-485 functionality.

### RS-232 modes

---

RS-232 supports following modes:

- [Log Mode](#) - suitable for debugging/logging;
- [NMEA](#) - NMEA logs are transferred;
- [LLS](#) - LLS sensor support;
- [LCD](#) - external LCD support;
- [RFID HID](#) - RFID HID reader support;
- [RFID MF7](#) - RFID MF7 reader support;
- [Garmin FMI](#) - Garmin support;
- [TCP ASCII](#) - for routing any input string from external device to the server;
- [TCP Binary](#) - for routing any binary input data from external device to the server.

## RS-232 baudrate and parity

Every RS-232 mode supports different baudrates, but each mode has its own default baudrate value. Default baudrate and parity values for each RS-232 mode are provided in the table below.

Mode	Default settings		
	RS-232	RS-485	
	Baudrate	Parity	Baudrate
<b>Log Mode</b>	115200	None	115200
<b>NMEA</b>	115200		115200
<b>LLS</b>	19200		19200
<b>LCD</b>	57600		-
<b>RFID HID</b>	57600		-
<b>RFID MF7</b>	9600		-
<b>Garmin FMI</b>	9600		-
<b>TCP ASCII</b>	115200		57600
<b>TCP Binary</b>	115200		57600

## RS-232 TCP Binary mode settings



RS-232 *TCP Binary mode* has additional configurable parameters for advanced data filtering as shown on the right hand side figure.

## RS-232 Garmin mode settings



*Garmin FMI mode* has additional filtering capabilities. It is possible to filter Ping and Unicode packets. If **Ping Filter** is enabled, then Ping packets are blocked. When **Unicode Filter** is enabled Unicode packets are not sent to the server. Both filters may be enabled for simultaneous effect.

## RS-485 modes

---

RS-485 supports several modes:

- **Log Mode** - suitable for debugging/logging;
- **NMEA** - NMEA logs are transferred;
- **LLS** - LLS sensors support;
- **TCP ASCII** - for routing any input string from external device to the server;
- **TCP Binary** - for routing any binary input data from external device to the server.

## RS-485 baudrate

Every RS-485 mode supports different baudrates, but each mode has its own default baudrate value. Default baudrate values for each RS-485 mode are provided in the table above.

## RS-485 LLS sensors



LLS addresses may be configured for 5 LLS sensors. If at least one LLS sensor is connected to FMC125 when configuring device using configurator, LLS sensor ID will be entered automatically. Up to 16 LLS sensors are supported with **03.28.XX** firmware version. Up to 8 passenger counter sensors "PP-01" can be connected each requiring 2 LLS addresses. The passenger counter sensor "PP-01" provides the possibility to count passengers getting either on or off public transport (bus, trolleybus, etc.).