

# TFT100 First Start

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**Small, professional and waterproof tracker for forklifts, E-mopeds and E-scooters with internal high gain GNSS/GSM antennas, Bluetooth® wireless technology, high capacity internal Li-ion battery and 10-97 V power supply range.**



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## Pinout

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TFT100 CAN PINOUT

TFT100 RS232 PINOUT

TFT100 RS485 PINOUT

TFT100 UART PINOUT


PIN COLOR	CAN PIN NAME	CAN DESCRIPTION	RS232 PIN NAME	RS232 DESCRIPTION	RS485 PIN NAME	RS485 DESCRIPTION	UART PIN NAME	UART DESCRIPTION
Red	VCC (10-97)V DC (+)	Power supply (+10...97 V DC).	VCC (10-97)V DC (+)	Power supply (+10...97 V DC).	VCC (10-97)V DC (+)	Power supply (+10...97 V DC).	VCC (10-97)V DC (+)	Power supply (+10...97 V DC).
Black	GND (-)	Ground.	GND (-)	Ground.	GND (-)	Ground.	GND (-)	Ground.
Yellow	1WIRE POWER	Power supply pin for Dallas 1-Wire devices	1WIRE POWER	Power supply pin for Dallas 1-Wire devices	1WIRE POWER	Power supply pin for Dallas 1-Wire devices	1WIRE POWER	Power supply pin for Dallas 1-Wire devices
White/Green	CAN-H	CAN interface High.	RS232-IN	Input wire for RS232.	RS485-B	Signal wire B for RS485.	UART-RX	Input for data reception through UART.
White	CAN-L	CAN interface Low.	RS232-OUT	Output wire for RS232.	RS485-A	Signal wire A for RS485.	UART-TX	Output for data transmission through UART.
Grey	AIN 2 / DIN 2	Analog input, channel 2 / Digital input, channel 2.	AIN 2 / DIN 2	Analog input, channel 2 / Digital input, channel 2.	AIN 2 / DIN 2	Analog input, channel 2 / Digital input, channel 2.	AIN 2 / DIN 2	Analog input, channel 2 / Digital input, channel 2.
White/Orange	DOUT 1 / DIN 3	Digital output, channel 1 / Digital input, channel 3.	DOUT 1 / DIN 3	Digital output, channel 1 / Digital input, channel 3.	DOUT 1 / DIN 3	Digital output, channel 1 / Digital input, channel 3.	DOUT 1 / DIN 3	Digital output, channel 1 / Digital input, channel 3.
Violet	DOUT 2 / DIN 4	Digital output, channel 2 / Digital input, channel 4.	DOUT 2 / DIN 4	Digital output, channel 2 / Digital input, channel 4.	DOUT 2 / DIN 4	Digital output, channel 2 / Digital input, channel 4.	DOUT 2 / DIN 4	Digital output, channel 2 / Digital input, channel 4.
Green	AIN 1 / DIN 1	Analog input, channel 1 / Digital input, channel 1.	AIN 1 / DIN 1	Analog input, channel 1 / Digital input, channel 1.	AIN 1 / DIN 1	Analog input, channel 1 / Digital input, channel 1.	AIN 1 / DIN 1	Analog input, channel 1 / Digital input, channel 1.
Blue	1WIRE DATA	Data channel for 1-Wire devices.	1WIRE DATA	Data channel for 1-Wire devices.	1WIRE DATA	Data channel for 1-Wire devices.	1WIRE DATA	Data channel for 1-Wire devices.

## Set up your device

## How to insert Micro-SIM card

1. **Remove** the bottom cover.
2. Insert **Micro-SIM** card as shown with **PIN request disabled** or read [Security info](#) how to enter it later in **Configurator**. Make sure that Micro-SIM card **cut-off corner** is pointing forward to slot.
3. Connect the **battery** as shown to the device.
4. After configuration, attach device **cover** and put the **screws** back in.
5. Device is ready to be connected.



 **Micro-SIM card insertion/removal must be performed when device is powered off - external voltage and battery are disconnected. Otherwise Micro-SIM card might be damaged or device will not detect it.**

## PC Connection (Windows)

1. Power-up TFT100 with **DC voltage 10 - 97V** power supply using **supplied power cable**. LED's should start blinking, see "**LED behaviour description**".
2. Connect device to computer using **Micro-USB cable** or **Bluetooth®** connection:
  - Using **Micro-USB cable**
    - You will need to install USB drivers, see "[How to install USB drivers \(Windows\)](#)"
  - Using **Bluetooth®**
    - TFT100 Bluetooth® is enabled by default. Turn on **Bluetooth®** on your PC, then select **Add Bluetooth® or other device > Bluetooth®**. Choose your device named - "**TFT100\_last\_7\_imei\_digits**", without **LE** in the end. Enter default password **5555**, press **Connect** and then select **Done**.
3. You are now ready to use the device on your computer.

## How to install USB drivers (Windows)

1. Please download COM port drivers from [here](#).
2. Extract and run **TeltonikaCOMDriver.exe**.
3. Click **Next** in driver installation window.
4. In the following window click **Install** button.
5. Setup will continue installing the driver and eventually the confirmation window will appear. Click **Finish** to complete the setup.

## Configuration (Windows)

At first TFT100 device will have default factory settings set. These settings should be changed according to the user's needs.

Main configuration can be performed via [Teltonika Configurator](#) software. Get the latest TFT100 **Configurator** version from [here](#). Configurator operates on Microsoft Windows OS and uses prerequisite MS .NET Framework. Make sure you have the correct version installed.

### [MS .NET requirements](#)

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Operating system	MS .NET Framework version	Version	Link
• Windows Vista	MS .NET Framework 4.6.2	32 and 64 bit	<a href="#">.NET Framework</a>
• Windows 7			
• Windows 8.1			
• Windows 10			

Downloaded **Configurator** will be in compressed archive. Extract it and launch **Configurator.exe**.

After launch software language can be changed by clicking  in the right bottom corner:











Configuration process begins by pressing on connected device:



After connection to Configurator **Status window** will be displayed: 

Various **Status window** tabs display information about **GNSS**, **GSM**, **I/O**, **Maintenance** and etc. TFT100 has one user editable profile, which can be loaded and saved to the device. After any modification of configuration the changes need to be saved to device using **Save to device** button. Main buttons offer following functionality:

1.  **Load from device** - loads configuration from device.
2.  **Save to device** - saves configuration to device.
3.  **Load from file** - loads configuration from file.
4.  **Save to file** - saves configuration to file.
5.  **Update firmware** - updates firmware on device.
6.  **Read records** - read records from device.
7.  **Reboot device** - restarts device.
8.  **Reset configuration** - sets device configuration to default.

Most important configurator section is GPRS - where all your server and **GPRS settings** can be configured and **Data Acquisition** - where data acquiring parameters can be configured. More details about TFT100 configuration using Configurator can be found **in the manual**.

## Quick SMS configuration

Default configuration has optimal parameters present to ensure best performance of track quality and data usage.

Quickly set up your device by sending this SMS command to it:

" setparam

2001:APN;2002:APN\_username;2003:APN\_password;2004:Domain;2005:Port;2006:0"

GPRS settings:

- 2001 - APN
- 2002 - APN username (if there are no APN username, empty field should be left)
- 2003 - APN password (if there are no APN password, empty field should be left)

Server settings:

- 2004 - Domain
- 2005 - Port
- 2006 - Data sending protocol (0 - TCP, 1 - UDP)

**Note:** Before SMS text, two space symbols should be inserted.



### Default configuration settings

Movement and ignition detection:

- |   |   |
|---|---|
| <input type="checkbox"/> Vehicle movement will be detected by accelerometer | <input type="checkbox"/> Ignition will be detected by vehicle power voltage between 13,2 - 30 V |
|---|---|

Device makes a record **On Moving** if one of these events happen:

- |  |  |
|--|--|
| <input type="checkbox"/> 300 seconds passes        | <input type="checkbox"/> Vehicle turns 10° degrees   |
| <input type="checkbox"/> Vehicle drives 100 meters | <input type="checkbox"/> Speed difference between last coordinate and current position is greater than 10 km/h |

Device makes a record **On Stop** if:

- ☐ 1 hour passes while vehicle is stationary and ignition is off

Records sending to server:

- ☐ If device has made a record it is sent to the server every 120 seconds

After successful SMS configuration, TFT100 device will **synchronize time** and **update records** to **configured server**. Time intervals and default I/O elements can be changed by using [Teltonika Configurator](#) or [SMS parameters](#).

## Mounting recommendations

- Connecting wires
  - Wires should be connected while the module is not plugged in.
- Wires should be fastened to stable wires or other non-moving parts. Any heat emitting and/or moving objects should be kept away from the wires.

- There should be no exposed wires. If factory isolation was removed while connecting wires, the isolation material should be applied.
  - If the wires are placed in the exterior or in places where they can be damaged or exposed to heat, humidity, dirt, etc., additional isolation should be applied and the wires should not be loose.
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- Connecting ignition wire
    - Be sure to check if it is a real ignition wire i. e. power does not disappear after starting the engine.
    - Check if this is not an ACC wire (when key is in the first position, most of the vehicle electronics are available).
    - Check if power is still available when you turn off any of vehicles devices.
    - Ignition is connected to the ignition relay output. As alternative, any other relay, which has power output when ignition is on, may be chosen.
- 
- Connecting ground wire
    - Ground wire is connected to the vehicle frame or metal parts that are fixed to the frame.
    - If the wire is fixed with the bolt, the loop must be connected to the end of the wire.
    - For better contact scrub paint from the spot where loop is going to be connected.

**PAY ATTENTION! Connecting the power supply must be carried out in a very low impedance point of on-board vehicle network. These points in the car are the battery terminals. Therefore, we recommend connecting the power of TFT100 (GND and POWER wires) directly to the battery terminals. Another valid option is to connect the wires to the main POWER cable inside the fuse box (if there is none, then to the power supply where the fuses of vehicle's computer are), GND wire must be connected in a special point, designed to connect GND vehicle computer. Connecting the GND at an arbitrary point to the mass of the car is unacceptable, as static and dynamic potentials on the line GND will be unpredictable, which can lead to unstable TFT100 operation and even its failure.**