Template:FMA110 I/O settings

When no I/O element is enabled, AVL packet comes with GNSS information only. After enabling I/O element(s) AVL packet along with GNSS information contains current value(s) of enabled I/O element.

	Permanent I/O elements (are always sent to server if enabled)							
No.	Property Name	Description						
01	Digital Input Status 1	Logic: 0 / 1						
02	Digital Input Status 2	Logic: 0 / 1						
03	Digital Input Status 3	Logic: 0 / 1						
04	Analog Input 1	Voltage: mV, 0 - 30 V						
05	Digital Output 1	Logic: 0 / 1						
06	Digital Output 2	Logic: 0 / 1						
07	GNSS PDOP	Probability * 10; 0-500						
80	GNSS HDOP	Probability * 10; 0-500						
09	External Voltage	Voltage: mV, 0 - 30 V						
10	GNSS Status	States: 0 - off state (when GPS module is off) 1 - Reserved 2 - GPS ready (antenna is working, but with no GPS fix) 3 - GPS working (antenna is working and has GPS fix) 4 - GPS sleep (when device is in GPS sleep mode) 5 - Overcurrent (The only condition to get value 5, then antenna is damaged and short circuit)						
11	Movement Sensor	0 – not moving, 1 – moving.						
12	Trip distance	Distance between two records: m						
13	GSM Operator	Currently used GSM Operator code						
14	Speed (Km/h)	Value in km/h, 0 - xxx km/h						
15	iButton ID	iButton ID number						
16	Mode	0 - home on stop, 1 - home on move, 2 - roaming on stop, 3 - roaming on move, 4 - unknown on stop, 5 - unknown on move						
17	GSM Signal	GSM signal level value in scale 1 - 5						
18	Deep Sleep	0 - not deep sleep mode, 1 - deep sleep mode						
19	Cell ID	GSM base station ID						
20	Area Code	Location Area code (LAC), it depends on GSM operator. It provides unique number which assigned to a set of base GSM stations. Max value: 65536						
21	Dallas Temperature 1	10 * Degrees (°C), -55 - +115, if 3000 - Dallas error						

22 Ignition Ignition status indication. Logic: 0 / 1 23 Total distance Distance which device has been traveled with ignition ON: m **24** Reserved IO 1 Reserved for future use 25 Reserved IO 2 Reserved for future use 26 Dallas Temperature 2 10 * Degrees (°C), -55 - +115, if 3000 - Dallas error 10 * Degrees (°C), -55 - +115, if 3000 - Dallas error 27 Dallas Temperature 3 28 Dallas Temperature 4 10 * Degrees (°C), -55 - +115, if 3000 - Dallas error 29 Dallas temperature ID1 1st connected dallas temperature sensor ID **30** Dallas temperature ID2 2nd connected dallas temperature sensor ID **31** Dallas temperature ID3 3rd connected dallas temperature sensor ID 32 Dallas temperature ID4 4rd connected dallas temperature sensor ID Eventual I/O elements (generate and send record to server only if appropriate conditions are met) Event: 0 - target left zone, 1 - target entered zone **33** Geofence zone 01 **34** Geofence zone 02 Event: 0 - target left zone, 1 - target entered zone **35** Geofence zone 03 Event: 0 - target left zone, 1 - target entered zone **36** Geofence zone 04 Event: 0 - target left zone, 1 - target entered zone **37** Geofence zone 05 Event: 0 - target left zone, 1 - target entered zone **38** Auto Geofence Event: 0 - target left zone, 1 - target entered zone **39** Trip 1 - trip start, 0 - trip stop 40 Immobilizer 1 - iButton connected **41** Authorized driving 1 - authorized iButton connected **42** Green driving type 1 - harsh acceleration, 2 - harsh braking, 3 - harsh cornering 43 Green driving value Depending on green driving type: if harsh acceleration or braking - g*100 (value 123 -> 1.23g), if harsh cornering - degrees (value in radians) 44 Over Speeding At over speeding start km/h, at over speeding end km/h **45** LVCAN Speed Value in km/h, 0 – 250 km/h**46** LVCAN Accelerator pedal position Value range: 0-100 % 47 LVCAN Total fuel used Value range: 0- 99999999 liters* "Total Fuel Used" is sent to server multiplied by 10. Example: if value was 150.5 liters, "1505" will be sent to server. **48** LVCAN Fuel level (liters) Value range: 0-100 liters Value range: 0-8200 rpm **49** LVCAN Engine RPM **50** LVCAN Vehicle distance Value range: 0-2145000000 meters Value range: 0-100 % **51** LVCAN Fuel level (proc.) 52 LVCAN Program number Value range: 0-999 **53** LVC ModuleID Value range: 0-max **54** LVC Engine Work Time Value range: 0-4294967295 **55** LVC Engine Work Time (counted) Value range: 0-4294967295

Value range: 0-4294967295

Value range: 0-4294967295

56 LVC Total Mileage (counted)

57 LVC Fuel Consumed (counted)

58	LVC Fuel Rate	Value range: 0-4294967295							
59	LVC AdBlue Level (percent)	Value range: 0-4294967295							
60	LVC AdBlue Level (liters)	Value range: 0-255							
61	LVC Engine Load	Value range: 0-65535							
62	LVC Engine Temperature	Value range: 0-65535							
63	LVC Axle 1 Load	Value range: 0-255							
64	LVC Axle 2 Load	Value range: 0-65535							
65	LVC Axle 3 Load	Value range: 0-65535							
66	LVC Axle 4 Load	Value range: 0-255							
67	LVC Axle 5 Load	Value range: 0-65535							
68	LVC Control State Flags	Value range: 0-255							
69	LVC Agricultural Machinery Flags	Value range: 0-255							
70	LVC Harvesting Time	Value range: 0-65535							
71	LVC Area of Harvest	Value range: 0-65535							
72	LVC Mowing Efficiency	Value range: 0-65535							
73	LVC Grain Mown Volume	Value range: 0-65535							
74	LVC Grain Moisture	Value range: 0-65535							
75	LVC Harvesting Drum RPM	Value range: 0-4294967295							
76	LVC Gap Under Harvesting Drum	Value range: 0-max							
77	LVC Security State Flags	Value range: 0-4294967295							
78	LVC Tacho Total Vehicle Distance	Value range: 0-4294967295							
79	LVC Trip Distance	Value range: 0-4294967295							
80	LVC Tacho Vehicle Speed	Value range: 0-4294967295							
81	LVC Tacho Driver Card Presence	Value range: 0-65535							
82	LVC Driver1 States	Value range: 0-65535							
83	LVC Driver2 States	Value range: 0-255							
84	LVC Driver1 Continuous Driving Time	Value range: 0-max							
85	LVC Driver2 Continuous Driving Time	Value range: 0-4294967295							
86	LVC Driver1 Cumulative Break Time	Value range: 0-4294967295							
87	LVC Driver2 Cumulative Break Time	Value range: 0-65535							
88	LVC Driver1 Duration Of Selected Action	Value range: 0-255							
89	LVC Driver2 Duration Of Selected	Value range: 0-255							
00	Action	varao rango. o 200							
90	LVC Driver1 Cumulative Driving Time	Value range: 0-255							
91	LVC Driver2 Cumulative Driving Time	Value range: 0-65535							
92	LVC Driver1 ID High	Value range: 0-65535							
93	LVC Driver1 ID Low	Value range: 0-65535							
94	LVC Driver2 ID High	Value range: 0-65535							
95	LVC Driver2 ID Low	Value range: 0-65535							
96	LVC Battery Temperature	Value range: 0-65535							
97	LVC Battery Level (percent)	Value range: 0-65535							

Note: There are two types of operations with Permanent I/O elements: simple monitoring and event generating. Monitoring method is used when current I/O information needed with regular GNSS coordinates. Event generating method is used when additional AVL packet is needed when current value of I/O exceeds predefined High and Low levels. I/O settings allow defining I/O event criteria.

System	Property Input	Enabled	Priority	L	ow Level		High Level	Generate Event		Averaging Constant	
Records	GNSS PDOP		Disable v	-	0	¢	0 0	Monitoring	-	10	-
GSM	GNSS HDOP		Disable =	-		A		Monitoring	-	10	
DataAcquisitionModes	External voltage		Disable =	-	10000	^	30000 \$	On Exit	Ŧ	10	
DataAcquisitionModes	GNSS power		Disable *	-	0	^	0 \$	Monitoring	7		
Features	Movement sensor		Disable +	-	0	\$	0 \$	Monitoring	Ŧ	10	h
10	Odometer value		Disable =	-	0	\$	0 \$	Monitoring	Ŧ		I
	GSM operator		Disable +	-	0	\$	0 \$	Monitoring	-		П
LVCAN	Speed (km/h)		Disable >	-	0	\$	0 \$	Monitoring	7	60	ı
	iButton ID		Disable +	-	0	^	5 \$	On Entrance	Ŧ	10	
	Mode		Disable v	-	0	^	0 \$	Monitoring	-		I

Enabled or disabled field – allows enabling I/O element so it is added to the data packet and is sent to the server. By default all I/O element are disabled and FM3612 records only GNSS coordinates.

Priority (AVL packet priority) can be low, high or panic. Regular packets are sent as Low priority records. When low priority event is triggered, FM3612 makes additional record with indication that the reason for that was I/O element change. When High priority is selected, module makes additional record with high priority flag and sends event packet immediately to the server by GPRS. Panic priority triggers same actions as high priority, but if GPRS fails, it sends AVL packet using SMS mode if SMS is enabled in SMS settings.

High and Low levels - define I/O value range. If I/O value enters or exits this range, FM3612 generates event. "Generate event" parameter defines when to generate event - when value enters defined range, exits it or both.

Averaging constant – it is an I/O event delay parameter. In some applications there is no need to generate events on every I/O range enter/exit immediately. Sometimes it is necessary to wait some time interval before event generating. Averaging constant allows setting I/O event delay (averaging). If I/O value is entering or leaving predefined range, it must have same value for Averaging constant time. 1 Averaging constant value equals about 30 miliseconds. In Deep Sleep mode there is no Averaging.

Note: Note: I/O element's "Movement sensor" Averaging constant is interpreted as Start Move

Timeout in seconds (from 1 to 59). Start Move Timeout – is a time interval required for movement sensor to be in the moving state, to consider vehicle as moving.

Monitoring

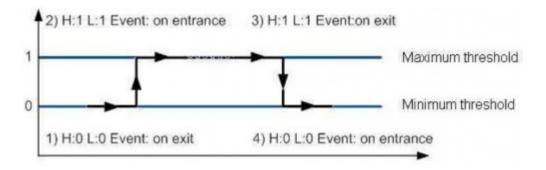
I/O monitoring starts after enabling I/O element and setting up I/O parameters as it is shown below:



Event generating

Events happen when the value of enabled I/O intersects thresholds (enter, exit or on both) predefined by High and Low level thresholds. Table below defines all available values of I/O settings.

Setting	Value
Priority	low, high
High level	maximum threshold
Low level	minimum threshold
Generate event	on interval enter, on interval exit, on both enter and exit
Average constant	t 1 - 2 ³² (4 Bytes)



Hysteresis



I/O elements can generate events according to hysteresis algorithm. If I/O event operand "Hysteresis" is selected, events will be generated as it is shown in the illustration below (I/O speed is taken as I/O value example):

