

DSM Configuration

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DSM calibration

If it is the first DSM launch, please make sure to calibrate the device, and change the important settings, to ensure the correct device working: [DSM Calibration](#)

Device configuration for FMx640

On this page, you will be able to find information about the general configuration and connection of DSM camera with the FMX640 tracking device. Information about different parameters required to set up the DSM camera are also described in this page. To start off, firstly follow the instructions on how to connect DSM camera with the FMX640 device, once the camera is connected to the tracking device, connect FMX640 to computer and open the required configurator application. Select your device and follow instructions below:

- It is necessary to change **Data Protocol** to [Codec 8 Extended](#) in the "System" tab.

Data Protocol



- In **RS232\RS485** settings under **RS232 Settings** navigate to **COM1 settings** and in **Mode** parameter selection, open the drop-down menu and select **DSM**, please also keep the baudrate set to default which is **115200**

| |
|--------------------------|
| Accelerometer Features |
| Auto Geofence |
| Manual Geofence Settings |
| Manual Geofence Zones |
| Trip \ Odometer |
| Bluetooth 4.0 |
| Beacon List |
| Authorization ID List |
| I/O |
| LVCAN |
| FMS IO |
| Manual CAN IO |
| Tachograph Data |
| RS232 \ RS485 |
| CAN \ Tachograph |
| ContiPressureCheck |
| Custom scenarios |
| Mobileye |
| Reefer IO |
| Euroscan IO |
| TK Touchprint IO |

RS485 Settings ?

| | | |
|----------|----------|---|
| Mode | Disabled | ▼ |
| Baudrate | Default | ▼ |

RS232 Settings ?

COM1 settings

| | | |
|----------|-------------|---|
| Mode | Silent Mode | ▼ |
| Baudrate | 115200 | ▼ |

COM2 settings

| | | |
|----------|-------------|---|
| Mode | Silent Mode | ▼ |
| Baudrate | 115200 | ▼ |

- Make sure to change **DSM I/O** feature **Priorities** to *Low, High or Panic* (Based on your needs). Also set operand and low/high settings in order to receive events based on specific conditions, e.g.: **Yawning - Low priority - Low/High level 0 - Operand On Exit**. This would mean that if the person yawns, the camera will detect this scenario, the parameter level will jump from 0 to 1 and will exit the configured high level which is set on exit. This will generate an event and send it to the configured server.

| Features | DSM I/O | | | | | | | | | | | | |
|--------------------------|--------------------|--------------|----------|-----|------|-------|-----------|------------|------------|----|------------|-----------|----|
| Accelerometer Features | Input Name | Units | Priority | | | | Low Level | High Level | Event Only | | Operand | Avg Const | |
| Auto Geofence | Drowsiness | | None | Low | High | Panic | 0 | 0 | Yes | No | Monitoring | ▼ | |
| Manual Geofence Settings | Distraction | | None | Low | High | Panic | 0 | 0 | Yes | No | Monitoring | ▼ | |
| Manual Geofence Zones | Yawning | | None | Low | High | Panic | 0 | 0 | Yes | No | Monitoring | ▼ | |
| Trip \ Odometer | Phone | | None | Low | High | Panic | 0 | 0 | Yes | No | Monitoring | ▼ | |
| Bluetooth 4.0 | Smoking | | None | Low | High | Panic | 0 | 0 | Yes | No | Monitoring | ▼ | |
| Beacon List | Driver absence | | None | Low | High | Panic | 0 | 0 | Yes | No | Monitoring | ▼ | |
| Authorization ID List | Mask | | None | Low | High | Panic | 0 | 0 | Yes | No | Monitoring | ▼ | |
| I/O | G-sensor | | None | Low | High | Panic | 0 | 0 | Yes | No | Monitoring | ▼ | |
| LVCAN | Active driver name | | None | Low | High | Panic | | | Yes | No | Monitoring | ▼ | |
| FMS IO | Recording status | | None | Low | High | Panic | 0 | 0 | Yes | No | Monitoring | ▼ | |
| Manual CAN IO | GPS status | | None | Low | High | Panic | 0 | 0 | Yes | No | Monitoring | ▼ | |
| Tachograph Data | Speed | km/h or mi/h | None | Low | High | Panic | 0 | 0 | Yes | No | Monitoring | ▼ | 10 |
| RS232 \ RS485 | Error code | | None | Low | High | Panic | 0 | 0 | Yes | No | Monitoring | ▼ | |
| DSM | | | | | | | | | | | | | |
| DSM I/O | | | | | | | | | | | | | |

- In order to receive event data, a server has to be configured. Navigate to **GPRS** settings and

enter the server details under **Server #1 Settings**. Details such as domain name and port number are required to be entered.

The image shows two configuration panels. The top panel, 'Server #1 Settings', includes input fields for 'Domain' and 'Port' (set to 0), and radio buttons for 'Protocol' with 'TCP' selected. The bottom panel, 'Server #2 Settings', includes a 'Backup Server Mode' section with buttons for 'Disable', 'Backup', 'Duplicate' (selected), and 'EGTS'; a 'Backup Server Protocol' section with 'TCP' (selected) and 'UDP' buttons; and input fields for 'Backup Server Domain' and 'Backup Server Port' (set to 0).

DSM configuration for FMx650

(!) Required firmware version - 03.00.14.Rev.114. [Firmware errata.](#)

- Make sure **Data Protocol** is set to [Codec 8 Extended](#)

Data Protocol

The image shows two buttons for 'Data Protocol': 'Codec 8' (highlighted in blue) and 'Codec 8 Extended' (grey).

- In *RS232 \ RS485 settings tab*, make sure to enable **Camera interface** by "Enable", and select **DSM** in the Mode drop-down menu, afterwards **DSM COM1** and **Camera I/O** should appear in the tab list.

The image shows the 'RS232 \ RS485' settings tab. On the left is a vertical menu with options: 'Manual CAN Commands', 'Tachograph Data', 'RS232 \ RS485' (selected), 'CAN \ Tachograph', 'ContiPressureCheck', and 'Custom Scenarios'. On the right is the 'COM1 settings' panel, which includes a 'Camera interface' section with 'Disable' and 'Enable' buttons (the latter is highlighted), and two dropdown menus for 'Mode' (set to 'Silent Mode') and 'Baudrate' (set to 'Default').

- Make sure to change **Camera I/O** camera state **Priorities** to *Low*

Camera I/O

| Input Name | Units | Priority | | | |
|-------------------------|-------|----------|-----|------|-------|
| COM1 DSM Drowsiness | | None | Low | High | Panic |
| COM1 DSM Distraction | | None | Low | High | Panic |
| COM1 DSM Yawning | | None | Low | High | Panic |
| COM1 DSM Phone | | None | Low | High | Panic |
| COM1 DSM Smoking | | None | Low | High | Panic |
| COM1 DSM Driver absence | | None | Low | High | Panic |
| COM1 DSM Mask | | None | Low | High | Panic |
| | | | | | |

- In appeared *DSM COM1* tab, make sure to **configure everything by your needs**, and do not forget to complete the "**Domain**" and "**Port**" settings in *File upload settings*



- **NOTE:** This is a base setup for the device to work properly. Other device configuration is made according to your needs.

Connecting two cameras simultaneously for FMx650

The new feature for FMx650 DSM configuration, which is available from **03.00.14.Rev.114 iCamera** allows you to connect two of your cameras at once. Method for connection and configuration stays the same, for this you are only required to choose **two** cameras in "**RS232 \ RS485**" tab from the configurator.

In the new functionality, you are able to connect any combo of the cameras by your wish, as an example: you are able to connect *DSM/Dualcam*, *DashCam/DualCam*, *DSM/DSM*, *DualCam/DualCam* and etc.

Manual CAN IO
Manual CAN Requests
Manual CAN Commands
Tachograph Data
RS232 \ RS485
CAN \ Tachograph
ContiPressureCheck
Custom Scenarios
Mobileye
Reefer IO
Transcan 2 IO
Transcan Advance IO
Euroscan IO
TK Touchprint IO
Simbiotecha PLC IO

RS232 Settings ⓘ

COM1 settings

Camera interface

Disable
Enable

Mode Silent Mode ▼

Baudrate Default ▼

COM2 settings

Camera interface

Disable
Enable

Mode Silent Mode ▼

Baudrate Default ▼

General settings

General settings

Measurement units

Metric
Imperial

Volume level ▲ ▼

Camera block repeat alarm

Disable
Enable

- Measurement Units - can either be metric or imperial, Global standard are metric units while in some cases like US and UK - measurement standard is Imperial units.
- Volume level - sets the volume level of DSM camera alerts
- Camera block repeat alarm - DSM camera will release a warning sound if the camera is blocked. This setting allows the camera to repeat warnings until the camera view is clear.

Image/recording settings

Image/recording settings

Voice recording

Disable Enable

Overlay text

Disable Enable

Mirror display

Disable Enable

Video format

NTSC PAL

Recording ratio 8:1:1 ▼

G-sensor sensitivity 1 ▲▼

- Voice recording - Enable voice recording on event activation.
- Overlay text - Shows overlay text for time and date on the picture.
- Mirror display - A choice whether the camera should take mirrored images or not.
- Video format - A choice of video format depending on the region.
- Recording ratio - Choose what type of files should occupy the SD card mostly. 1st number is continuous footage, 2nd one is g-sensor data and 3rd is DSM event footage data.
- G-sensor sensitivity - Camera has its own sensor to detect crashes and its sensitivity can be adjusted.

Event settings

Event settings

Working speed source

Global Individual

Working speed (global) (km/h) 0 ▲▼

Automatic transmit (global)

Disable Enable

- Working speed source - **Global** setting will set the same speed limit for all of the settings which require speed limit for activation while **Individual** settings will allow each parameter to have its own configurable speed limit setting for their events.
- Automatic transmit (global) - Global setting for automatic image transmission when the event is active, only works for events that do not have this setting (**Yawning**).

Drowsiness

Drowsiness

Function

Disable

Enable

Sound

0

Vibration

Disable

Enable

Sensitivity

1

Automatic transmit

Disable

Enable

Working speed (km/h)

0

- Activation - Enables or disables Drowsiness function, Sound type of each event can also be changed (0,1,2 or 3 (voice) types).
- Vibration - Upon Drowsiness event activation, vibration can also be activated.
- Sensitivity - this parameter is for the Drowsiness sensitivity setting 1-3 (1- lowest, 3 - highest).
- Automatic transmit - Transmits images to the server when the event is active. Also has working speed parameter which sets the minimum required speed for the event to become enabled, leave 0 for this setting to be off.

Distraction

Distraction

Function

Disable

Enable

Sound

0

Vibration

Disable

Enable

Sensitivity

1

Automatic transmit

Disable

Enable

Working speed (km/h)

0

- Activation - Enables or disables Distraction function, Sound type of each event can also be changed (0,1,2 or 3 (voice) types).
- Vibration - Upon Distraction event activation, vibration can also be activated.
- Sensitivity - this parameter is for the Distraction sensitivity setting 1-3 (1- lowest, 3 - highest).
- Automatic transmit - Transmits images to the server when the event is active. Also has working speed parameter which sets the minimum required speed for the event to become enabled, leave 0 for this setting to be off.

Phone

Phone

Function

| | |
|---------|--------|
| Disable | Enable |
|---------|--------|

Sound

Vibration

| | |
|---------|--------|
| Disable | Enable |
|---------|--------|

Sensitivity

Automatic transmit

| | |
|---------|--------|
| Disable | Enable |
|---------|--------|

Working speed (km/h)

- Activation - Enables or disables Phone function, Sound type of each event can also be changed (0,1,2 or 3 (voice) types).
- Vibration - Upon Phone event activation, vibration can also be activated.
- Sensitivity - this parameter is for the Phone sensitivity setting 1-3 (1- lowest, 3 - highest).
- Automatic transmit - Transmits images to the server when the event is active. Also has working speed parameter which sets the minimum required speed for the Phone event to become enabled, leave 0 for this setting to be off.

Smoking

Smoking

Function

| | |
|---------|--------|
| Disable | Enable |
|---------|--------|

Sound

Vibration

| | |
|---------|--------|
| Disable | Enable |
|---------|--------|

Sensitivity

Automatic transmit

| | |
|---------|--------|
| Disable | Enable |
|---------|--------|

Working speed (km/h)

- Activation - Enables or disables Smoking function, Sound type of each event can also be changed (0,1,2 or 3 (voice) types).
- Vibration - Upon Smoking event activation, vibration can also be activated.
- Sensitivity - this parameter is for the Smoking sensitivity setting 1-3 (1- lowest, 3 - highest).

- Automatic transmit - Transmits images to the server when the event is active. Also has working speed parameter which sets the minimum required speed for the Smoking event to become enabled, leave 0 for this setting to be off.

Yawning

Yawning

Function

Disable
Enable

Sound
0

Vibration

Disable
Enable

Sensitivity
1

Working speed (km/h)
0

- Activation - Enables or disables Yawning function, Sound type of each event can also be changed (0,1,2 or 3 (voice) types).
- Vibration - Upon Yawning event activation, vibration can also be activated.
- Sensitivity - this parameter is for the Yawing sensitivity setting 1-3 (1- lowest, 3 - highest).
- Working speed - Working speed parameter which sets the minimum required speed for the Smoking event to become enabled, leave 0 for this setting to be off. **Note:** This parameter does not have Automatic transmit parameter, therefore, upon activation, this event is not going to be configured to send images/audio to the server, however this setting can be activated in **Event settings** under Automatic transmit (Global) parameter.

File upload settings

This section is meant for image sending only, parameter data sending if configured, is done through GPRS settings tab where most of data is configured for sending.

File upload settings

Domain

Port

Periodic image sending

Sending interval (s)

Image sending trigger

| | |
|--------|---------------|
| DIN1 | DIN2 |
| DIN3 | DIN4 |
| Crash | Towing |
| Idling | Geofence |
| Unplug | Green driving |

- Domain - Domain name where the image/audio files should be sent, can be a website or IP address (e.g. 123.123.12.198).
- Port - Port number which is assigned to a domain name and works as an entry point to the server.
- Periodic image sending - Periodic image sending can be sent in order to send images to the server at a configurable time period.
- Image sending trigger - Triggers can be set in order to activate image sending. Crash/Towing/Idling/Geofence/Unplug/Green driving are actual features of the FMX640 family devices and are configured under [Features](#) / [Accelerometer Features](#) / [Geofence](#) / [Trip/Odometer](#) Tabs.

Crash Detection Functionality using DOUT

The crash detection feature is a crucial capability provided by our device. It enhances evidential documentation through video or photo evidence in the event of a crash. However, activating this functionality necessitates a direct connection of the camera to a power source. Nonetheless, such a direct connection can lead to **battery drainage**.

To circumvent this issue, we recommend utilizing DOUT and a relay for connection. This setup enables control via SMS or GPRS command, or through predefined scenarios within our device. By activating DOUT post-ignition, the camera receives power, allowing it to function and record evidence even after the ignition is turned off following a crash. **For your convenience, the connection scheme can be found here: [DSM First Start](#)**

It is important to note that in the event of a fatal crash where fatalities may occur, we cannot guarantee the retrieval of video or photo evidence due to the severity of the accident. Moreover, both the camera and the device itself may sustain irreparable damage in such instances