

Template:FMB208 Auto Geofence settings

Auto Geofence

Scenario Settings

Disable	Low Priority
High Priority	Panic Priority

Eventual Records

Disable	Enable
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Generate Event

On Exit	On Entrance
On Both	

Activation Timeout (s)

60

Radius (m)

100

Deactivate By

Power Voltage	Engine RPM
Digital Input 1	Digital Input 2

Send SMS To

SMS Text

AutoGeofence

AutoGeofence is based on the last known position after the movement has stopped. You can be notified using this function if your car is taken away. The shape and size of Geofence zones are set by parameters. It is possible to state whether entering or leaving the geofence triggers an asynchronous message. AutoGeofencing options can be configured by following parameters as depicted in the right hand side figure:

Activation timeout defines the delay between the creation of AutoGeofence within set *Radius* value around vehicle's most recent position and when the ignition is off. Note that AutoGeofencing does not require entering coordinates, instead it requires GPS visibility. Event generation can take place on Geofence **Entrance**, **Exit** or **On Both**. *Eventual Records* is used to enable or disable *Eventual Records* functionality. AutoGeofence can be deactivated by:

- **Power Voltage** - If power voltage becomes higher than low voltage level (defined in Ignition settings).
- **Engine RPM** - If engine RPM value becomes higher than 0.
- **Digital Input 1** - If DIN2 voltage becomes equal or higher than 2.5 V.
- **Digital Input 2** - If DIN3 voltage becomes equal or higher than 2.5 V.